On Strongly Regular Graphs, Friendship, and the Shannon Capacity

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Graph Spectrum

Throughout this presentation,

- G = (V(G), E(G)) is a finite, undirected, and simple graph of order |V(G)| = n and size |E(G)| = m.
- $\mathbf{A} = \mathbf{A}(\mathsf{G})$ is the *adjacency matrix* of the graph.
- ${\ensuremath{\, \bullet }}$ The eigenvalues of ${\ensuremath{\, A}}$ are given in decreasing order by

$$\lambda_{\max}(\mathsf{G}) = \lambda_1(\mathsf{G}) \ge \lambda_2(\mathsf{G}) \ge \ldots \ge \lambda_n(\mathsf{G}) = \lambda_{\min}(\mathsf{G}).$$
 (1.1)

• The *spectrum* of G is a multiset that consists of all the eigenvalues of **A**, including their multiplicities.

Orthogonal Representation of Graphs

Definition 1.1

Let G be a finite, undirected and simple graph. An orthogonal representation of G in \mathbb{R}^d

$$i \in \mathsf{V}(\mathsf{G}) \mapsto \mathbf{u}_i \in \mathbb{R}^d$$

such that

$$\mathbf{u}_i^{\mathrm{T}}\mathbf{u}_j = 0, \quad \forall \left\{ i, j \right\} \notin \mathsf{E}(\mathsf{G}).$$

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In an orthogonal representation of a graph G:

- non-adjacent vertices: mapped to orthogonal vectors;
- adjacent vertices: not necessarily mapped to non-orthogonal vectors.

Lovász ϑ -function

Let G be a finite, undirected and simple graph.

The Lovász ϑ -function of G is defined as

$$\vartheta(\mathsf{G}) \triangleq \min_{\mathbf{u},\mathbf{c}} \max_{i \in \mathsf{V}(\mathsf{G})} \frac{1}{\left(\mathbf{c}^{\mathrm{T}}\mathbf{u}_{i}\right)^{2}},$$

where the minimum is taken over

- \bullet all orthonormal representations $\{\mathbf{u}_i:i\in\mathsf{V}(\mathsf{G})\}$ of $\mathsf{G},$ and
- all unit vectors c.

The unit vector \mathbf{c} is called the *handle* of the orthonormal representation.

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$$|\mathbf{c}^{\mathrm{T}}\mathbf{u}_i| \leq ||\mathbf{c}|| ||\mathbf{u}_i|| = 1 \implies \vartheta(\mathsf{G}) \geq 1,$$

with equality if and only if G is a complete graph.

(1.2)

An Orthonormal Representation of a Pentagon

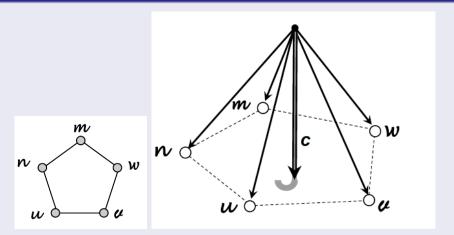


Figure 1: A 5-cycle graph and its orthonormal representation (also known as Lovász umbrella). Calculation shows that $\vartheta(C_5) = \sqrt{5}$ (Lovász, 1979).

- A is the $n \times n$ adjacency matrix of G $(n \triangleq |V(G)|)$;
- \mathbf{J}_n is the all-ones $n \times n$ matrix;
- \mathcal{S}^n_+ is the set of all $n \times n$ positive semidefinite matrices.

Semidefinite program (SDP), with strong duality, for computing $\vartheta(G)$:

 $\begin{array}{l} \text{maximize Trace}(\mathbf{B} \mathbf{J}_n) \\ \text{subject to} \\ \begin{cases} \mathbf{B} \in \mathcal{S}^n_+, \ \text{Trace}(\mathbf{B}) = 1, \\ A_{i,j} = 1 \ \Rightarrow \ B_{i,j} = 0, \quad i, j \in [n]. \end{cases} \end{cases}$

Computational complexity: \exists algorithm (based on the ellipsoid method) that numerically computes $\vartheta(G)$, for every graph G, with precision of r decimal digits, and polynomial-time in n and r.

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Let $\alpha(G)$, $\omega(G)$, and $\chi(G)$ denote the independence number, clique number, and chromatic number of a graph G. Then,

Sandwich theorem:

$$\alpha(\mathsf{G}) \le \vartheta(\mathsf{G}) \le \chi(\overline{\mathsf{G}}),\tag{1.3}$$

$$\omega(\mathsf{G}) \le \vartheta(\overline{\mathsf{G}}) \le \chi(\mathsf{G}). \tag{1.4}$$

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- Omputational complexity:
 - $\alpha(G)$, $\omega(G)$, and $\chi(G)$ are NP-hard problems.
 - ► However, the numerical computation of ϑ(G) is in general feasible by convex optimization (SDP problem).

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Hoffman-Lovász inequality: Let G be d-regular of order n. Then,

$$\vartheta(\mathsf{G}) \le -\frac{n\,\lambda_n(\mathsf{G})}{d - \lambda_n(\mathsf{G})},$$
(1.5)

with equality if G is edge-transitive.

Strongly Regular Graphs

Let G be a *d*-regular graph of order n. It is a *strongly regular* graph (SRG) if there exist nonnegative integers λ and μ such that

- Every pair of adjacent vertices have exactly λ common neighbors;
- Every pair of distinct and non-adjacent vertices have exactly μ common neighbors.

Such a strongly regular graph is denoted by $srg(n, d, \lambda, \mu)$.

Theorem 1.2 (Bounds on Lovász function of Regular Graphs, I.S., '23)

Let G be a *d*-regular graph of order *n*, which is a non-complete and non-empty graph. Then, the following bounds hold for the Lovász ϑ -function of G and its complement \overline{G} :

1)

$$\frac{n-d+\lambda_2(\mathsf{G})}{1+\lambda_2(\mathsf{G})} \le \vartheta(\mathsf{G}) \le -\frac{n\lambda_n(\mathsf{G})}{d-\lambda_n(\mathsf{G})}.$$
(1.6)

- Equality holds in the leftmost inequality if \overline{G} is both vertex-transitive and edge-transitive, or if G is a strongly regular graph;
- Equality holds in the rightmost inequality if G is edge-transitive, or if G is a strongly regular graph.

Cont. of Theorem 1.2

2)

$$1 - \frac{d}{\lambda_n(\mathsf{G})} \le \vartheta(\overline{\mathsf{G}}) \le \frac{n(1 + \lambda_2(\mathsf{G}))}{n - d + \lambda_2(\mathsf{G})}.$$
(1.7)

- Equality holds in the leftmost inequality if G is both vertex-transitive and edge-transitive, or if G is a strongly regular graph;
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A Common Sufficient Condition

All inequalities hold with equality if G is strongly regular. (Recall that the graph G is strongly regular if and only if \overline{G} is so).

Lovász Function of Strongly Regular Graphs (I.S., '23)

Let G be a strongly regular graph with parameters $\mathrm{srg}(n,d,\lambda,\mu).$ Then,

$$\vartheta(\mathsf{G}) = \frac{n\left(t + \mu - \lambda\right)}{2d + t + \mu - \lambda},\tag{1.8}$$

$$\vartheta(\overline{\mathsf{G}}) = 1 + \frac{2d}{t + \mu - \lambda},\tag{1.9}$$

where

$$t \triangleq \sqrt{(\mu - \lambda)^2 + 4(d - \mu)}.$$
(1.10)

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New Relation for Strongly Regular Graphs

$$\vartheta(\mathsf{G})\,\vartheta(\overline{\mathsf{G}}) = n,$$
 (1.11)

holding not only for all vertex-transitive graphs (Lovász '79), but also for all strongly regular graphs (that are not necessarily vertex-transitive).

We next provide an original proof of the following celebrated theorem by Erdös, Rényi and Sós (1966), based on our expression for the Lovász ϑ -function of strongly regular graphs (and their complements, which are also strongly regular graphs).

Theorem 1.3 (Friendship Theorem)

Let G be a finite graph in which any two distinct vertices have a single common neighbor. Then, G has a vertex that is adjacent to every other vertex.

We next provide an original proof of the following celebrated theorem by Erdös, Rényi and Sós (1966), based on our expression for the Lovász ϑ -function of strongly regular graphs (and their complements, which are also strongly regular graphs).

Theorem 1.3 (Friendship Theorem)

Let G be a finite graph in which any two distinct vertices have a single common neighbor. Then, G has a vertex that is adjacent to every other vertex.

A Human Interpretation of Theorem 1.3

- There is a party with *n* people, where every two people have precisely one common friend in that party.
- Theorem 1.3 asserts that one of these people is everybody's friend.
- Indeed, construct a graph whose vertices represent the *n* people, and every two vertices are adjacent if and only if they represent two friends. The claim then follows from Theorem 1.3.

Remark 1 (On the Friendship Theorem - Theorem 1.3)

- The windmill graph (see Figure 2) has the desired property, and it turns out to be the only one graph with that property.
- The friendship theorem does not hold for infinite graphs.



Figure 2: Windmill graph.

Alternative Proof of Theorem 1.3 (I.S., '25)

Suppose the assertion is false, and G is a counterexample — a finite graph in which any two distinct vertices have a single common neighbor, yet no vertex in G is adjacent to all other vertices. A contradiction is obtained by the following proof outline:

- It is shown that the graph is regular.
- It is then shown that the graph is strongly regular srg(n, k, 1, 1).
- If k = 0 or k = 2, then $G = K_1$ or $G = K_3$, respectively, which satisfy the assertion of the theorem. Hence, next assume that $k \ge 3$.
- By the theorem hypothesis, it follows that $\omega(\mathsf{G})=\chi(\mathsf{G})=3.$
- By the sandwich theorem $\omega(\mathsf{G}) \leq \vartheta(\overline{\mathsf{G}}) \leq \chi(\mathsf{G})$, so $\vartheta(\overline{\mathsf{G}}) = 3$.
- Based on the expression for the Lovász ϑ -function $\vartheta(\overline{\mathsf{G}}) = 1 + \frac{k}{\sqrt{k-1}}$.
- This leads to a contradiction for all $k \ge 3$.

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The sandwich theorem for the Lovász ϑ -function applied to strongly regular graphs gives the following result.

Corollary 1.4 (Bounds on Parameters of SRGs)

Let G be a strongly regular graph with parameters $\mathrm{srg}(n,d,\lambda,\mu).$ Then,

$$\alpha(\mathsf{G}) \le \left\lfloor \frac{n\left(t+\mu-\lambda\right)}{2d+t+\mu-\lambda} \right\rfloor \tag{1.12}$$

$$\omega(\mathsf{G}) \le 1 + \left\lfloor \frac{2d}{t + \mu - \lambda} \right\rfloor,\tag{1.13}$$

$$\chi(\mathsf{G}) \ge 1 + \left\lceil \frac{2d}{t + \mu - \lambda} \right\rceil,\tag{1.14}$$

$$\chi(\overline{\mathsf{G}}) \ge \left\lceil \frac{n\left(t+\mu-\lambda\right)}{2d+t+\mu-\lambda} \right\rceil,\tag{1.15}$$

with

$$t \triangleq \sqrt{(\mu - \lambda)^2 + 4(d - \mu)}.$$
(1.16)

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Examples: Bounds on Parameters of SRGs

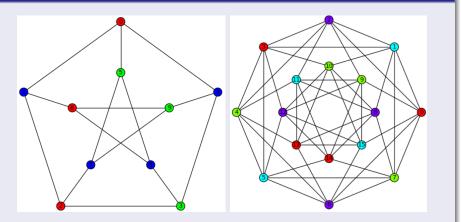


Figure 3: The Petersen graph is srg(10,3,0,1) (left), and the Shrikhande graph is srg(16,6,2,2) (right). Their chromatic numbers are 3 and 4, respectively.

Schläfli Graph

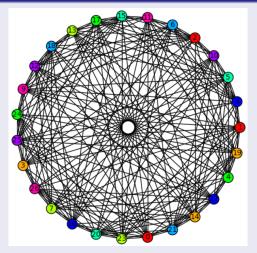


Figure 4: Schläfli graph is srg(27, 16, 10, 8) with chromatic number $\chi(G) = 9$.

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Examples: Bounds on Parameters of SRGs (Cont.)

 Let G₁ be the Petersen graph. Then, the bounds on the independence, clique, and chromatic numbers of G are tight:

$$\alpha(\mathsf{G}_1) = 4, \quad \omega(\mathsf{G}_1) = 2, \quad \chi(\mathsf{G}_1) = 3.$$
 (1.17)

The bounds on the chromatic numbers of the Schläfli graph (G₂), Shrikhande graph (G₃) and Hall-Janko graph (G₄) are tight:

$$\chi(\mathsf{G}_2) = 9, \quad \chi(\mathsf{G}_3) = 4, \quad \chi(\mathsf{G}_4) = 10.$$
 (1.18)

③ For the Shrikhande graph (G_3) ,

- the bound on its independence number is also tight: $\alpha(G_3) = 4$,
- ► its upper bound on its clique number is, however, not tight (it is equal to 4, and ω(G₃) = 3).

Strong Product of Graphs

Let G and H be two graphs. The strong product $G \boxtimes H$ is a graph with

- vertex set: $V(G \boxtimes H) = V(G) \times V(H)$,
- two distinct vertices (g,h) and (g',h') in $\mathsf{G}\boxtimes\mathsf{H}$ are adjacent if the following two conditions hold:

$$\ \, {\tt 0} \ \ \, g=g' \ {\tt or} \ \{g,g'\}\in {\sf E}({\sf G}),$$

Strong products are commutative and associative.

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Strong Powers of Graphs

Let

$$\mathsf{G}^{\boxtimes k} \triangleq \underbrace{\mathsf{G} \boxtimes \ldots \boxtimes \mathsf{G}}_{\mathsf{G} \text{ appears } k \text{ times}}, \quad k \in \mathbb{N}$$
(1.19)

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denote the k-fold strong power of a graph G.

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Shannon Capacity of a Graph (1956)

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- A channel is represented by a confusion graph G, where the vertices of G represent the input symbols and two vertices are adjacent if the corresponding pair of input symbols can be confused by the channel decoder). The Shannon capacity of a graph G is given by

$$\Theta(\mathsf{G}) = \sup_{k \in \mathbb{N}} \sqrt[k]{\alpha(\mathsf{G}^{\boxtimes k})}$$
$$= \lim_{k \to \infty} \sqrt[k]{\alpha(\mathsf{G}^{\boxtimes k})}.$$
(2.1)

Shannon Capacity of a Graph (1956)

- The capacity of a graph G was introduced by Claude E. Shannon (1956) to represent the maximum information rate that can be obtained with zero-error communication.
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$$= \lim_{k \to \infty} \sqrt[k]{\alpha(\mathsf{G}^{\boxtimes k})}.$$
(2.1)

• The last equality holds by Fekete's Lemma since the sequence $\{\log \alpha(\mathsf{G}^{\boxtimes k})\}_{k=1}^{\infty}$ is super-additive, i.e.,

$$\alpha(\mathsf{G}^{\boxtimes (k_1+k_2)}) \ge \alpha(\mathsf{G}^{\boxtimes k_1}) \ \alpha(\mathsf{G}^{\boxtimes k_2}). \tag{2.2}$$

On the Computability of the Shannon Capacity of Graphs

- ullet The Shannon capacity of a graph can be rarely computed exactly. igodot
- However, the Lovász ϑ-function of a graph is a computable (and sometimes tight) upper bound on the Shannon capacity. ☺

Lovász Bound on the Shannon Capacity of Graphs (1979)

Theorem: For every finite, simple and undirected graph G,

$$\alpha(\mathsf{G}) \le \Theta(\mathsf{G}) \le \vartheta(\mathsf{G}),\tag{2.3}$$

so if $\alpha(G) = \vartheta(G)$, then $\Theta(G) = \vartheta(G)$.

Shannon Capacities of Some Strongly Regular Graphs

- The Hall-Janko graph G is srg(100, 36, 14, 12), and $\Theta(G) = 10$.
- ② The Hoffman-Singleton graph G is srg(50, 7, 0, 1), and $\Theta(G) = 15$.
- The Janko-Kharaghani graphs of orders 936 and 1800 are srg(936, 375, 150, 150) and srg(1800, 1029, 588, 588), respectively. The capacity of both graphs is 36.
- I Janko-Kharaghani-Tonchev: $G = srg(324, 153, 72, 72), \Theta(G) = 18.$
- The graphs introduced by Makhnev are G = srg(64, 18, 2, 6) and $\overline{G} = srg(64, 45, 32, 30)$. Capacities: $\Theta(G) = 16$, and $\Theta(\overline{G}) = 4$.
- If the Mathon-Rosa graph G is srg(280, 117, 44, 52), and $\Theta(G) = 28$.
- **(**) The Schläfli graph G is srg(27, 16, 10, 8), and $\Theta(G) = 3$.
- **(a)** The Shrikhande graph is srg(16, 6, 2, 2); its capacity is $\Theta(G) = 4$.
- **(**) The Sims-Gewirtz graph G is srg(56, 10, 0, 2), and $\Theta(G) = 16$.
- **1** The graph G by Tonchev is srg(220, 84, 38, 28), and $\Theta(G) = 10$.

Theoretical results on the Shannon capacity of graphs are in the papers.

Recent Journal Papers

This talk relies on the following recent journal papers:

- I. Sason, "Observations on the Lovász ∂-function, graph capacity, eigenvalues, and strong products," *Entropy*, vol. 25, no. 1, paper 104, pp. 1-40, January 2023. https://doi.org/10.3390/e25010104
- I. Sason, "Observations on graph invariants with the Lovász θ-function," AIMS Mathematics, vol. 9, pp. 15385–15468, April 2024. https://www.aimspress.com/article/doi/10.3934/math.2024747
- I. Sason, "On strongly regular graphs and the friendship theorem," submitted, February 2025. https://arxiv.org/abs/2502.13596